IN THE SPECIFICATION:

Please amend page 1, last paragraph as follows:

There has heretofore been known a system in which in drive control of a brushless motor, the relationship of position between a rotor and a stator is detected using a [[hole]] Hall element and a coil phase to start its energization is determined from the detected positional relationship to thereby prevent the motor from being reversely rotated. However, since it becomes difficult to scale down or downsize the motor when a rotor position detector using the [[hole]] Hall element is attached to the motor, a sensorless motor is moving toward heavy use in the hard disk drive. In such a sensorless motor, the rotor might be reversely rotated upon starting of its rotation if the relationship of position between the rotor and stator is not recognized.

Please amend page 10, second paragraph as follows:

~~Fig. 2 is an~~ Figs. 2(a) and 2(b) are explanatory diagrams illustrating an energizing method for detecting the position of a rotor in the start-up control circuit according to the embodiment, and a method for detecting an induced voltage of a de-energized phase;

Please amend page 11, last two paragraphs as follows:

~~Fig. 14 is a~~ Figs. 14(A)-14(F) are timing charts illustrating timings of a triangular wave carrier signal, PWM control signals and a sample-and-hold signal employed in the motor drive control circuit according to the embodiment;

~~Fig. 15 is a~~ Figs. 15(A)-15(F) are timing charts showing the relationship between levels of PWM control signals of respective phases and detectable currents at respective sections obtained by dividing an electrical angle of 360° into six according to magnitudes of voltage values in the motor drive control circuit according to the embodiment;

Please amend page 13, second paragraph as follows:

~~Fig. 22 is a~~ Figs. 22(A)-22(G) are waveform diagrams showing the relationship between polarities of induced voltages and phases of back electromotive voltages in a general three-phase DC motor and a special three-phase DC motor;

Please amend page 38, first paragraph as follows:

Fig. 14(F) shows a waveform of a current detected by the sense resistor Rsns in the motor drive control circuit according to the present embodiment. It is understood that when this current waveform and a current waveform of Fig. ~~24(F)~~ 14(F)detected in the conventional motor drive control circuit are compared, accurate current values can be sampled with margins by the sample-and-hold signals SH in the case of the present embodiment rather than in the conventional example. In the present embodiment as well, as apparent from a comparison between Fig. 15 indicative of timings corresponding to Fig. 23 ~~and Fig. 23~~, phase currents respectively obtained by calculation can be detected even during sections in Fig. 23 undetectable due to phase lags between the pulse signals UPWM, VPWM and WPWM. Incidentally, even in the present embodiment, the coil currents for the two phases are detected by the sense resistor during the respective sections, and the coil current for the remaining phase may be obtained by calculation (e.g., iu = -iv-iw).